

Evolution + deep RL

Using evolution to optimize policies

Olivier Sigaud

Sorbonne Université
<http://people.isir.upmc.fr/sigaud>



Introduction

- ▶ RL methods follow a gradient, but do not evaluate the obtained agent
- ▶ Evolutionary methods perform random variations, but evaluate the agents
- ▶ Evo+RL: looking for the best of both worlds
- ▶ Four perspectives:
 - ▶ Evolving policies to improve performance
 - ▶ Evolving actions to improve performance
 - ▶ Evolving policies to improve diversity
 - ▶ Evolving something else (hyper-params, environment, reward function...)
- ▶ Older perspective: learning classifier systems



Sigaud, O. (2022) Combining evolution and deep reinforcement learning for policy search: a survey. *arXiv preprint arXiv:2203.14009*



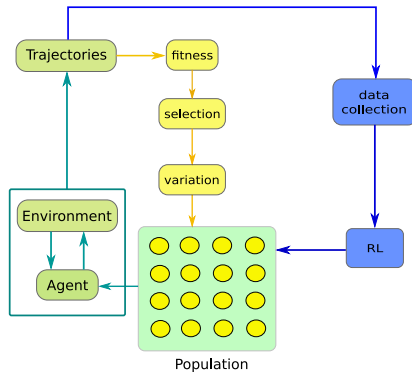
Sigaud, O. and Wilson, S. W. (2007) Learning classifier systems: A survey. *Journal of Soft Computing*, 11(11):1065–1078

Evolving policies to improve performance: overview

	Prop.	RL algo.	Evo. algo.	Actor Injec.	+ Comb. Mech.	Surr. Fitness	Soft Update	Buffer Filt.
ERL	Khadka and Tumer (2018)	DDPG	GA	•	x	x	x	x
CERL	Khadka et al. (2019)	TD3	GA	•	x	x	x	x
PDERL	Bodnar et al. (2020)	TD3	GA	•	x	x	x	x
ESAC	Suri et al. (2020)	SAC	ES	•	x	x	x	x
FIDI-RL	Shi et al. (2019)	DDPG	ARS	•	x	x	x	x
X-DDPG	Esposito and Bonarini (2020)	DDPG	GA	•	x	x	x	x
CEM-RL	Pourchot and Sigaud (2019)	TD3	CEM	x	•	x	x	x
CEM-ACER	Tang (2021)	ACER	CEM	x	•	x	x	x
SERL	Wang et al. (2022)	DDPG	GA	•	x	•	x	x
SPDERL	Wang et al. (2022)	TD3	GA	•	x	•	x	x
PGPS	Kim et al. (2020)	TD3	CEM	•	x	•	•	x
BNET	Stork et al. (2021)	BBNE	CPG	•	x	•	x	x
CSPG	Zheng et al. (2020)	SAC + PPO	CEM	•	x	x	x	•
SUPE-RL	Marchesini et al. (2021)	RAINBOW or PPO	GA	•	♠	x	•	x
G2AC	Chang et al. (2018)	A2C	GA	x	♠	x	x	x
G2PPO	Chang et al. (2018)	PPO	GA	x	♠	x	x	x

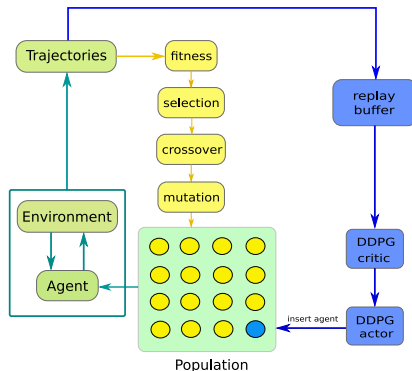
► The most active line of combinations

General architecture



- A template for many algorithms

The renewal of Evo+RL: ERL

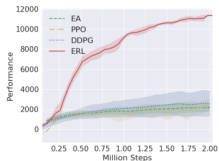


► One of the main Evo+RL approaches

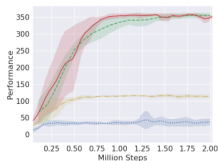


Khadka, S. & Tumer, K. (2018) Evolution-guided policy gradient in reinforcement learning. In *Neural Information Processing Systems*

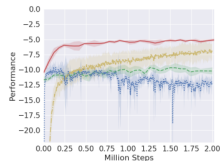
ERL results



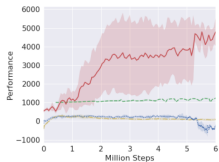
(a) HalfCheetah



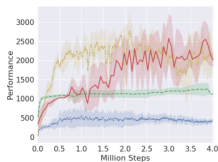
(b) Swimmer



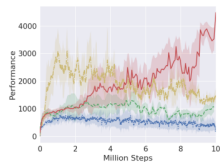
(c) Reacher



(d) Ant



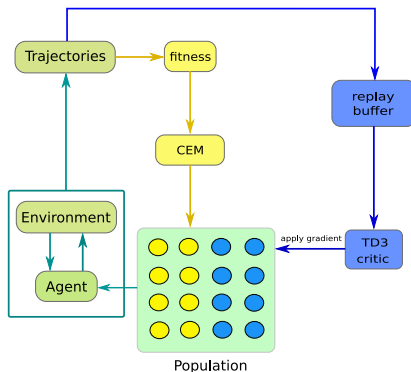
(e) Hopper



(f) Walker2D

- Consistent improvement in performance and sample efficiency

Competitor: CEM-RL

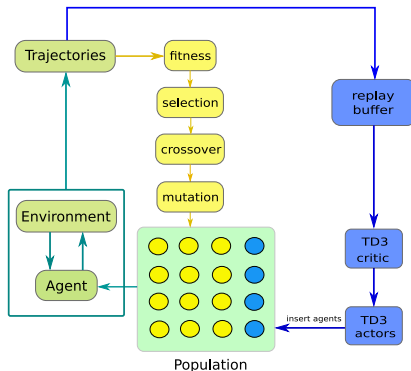


- Applies the TD3 critic gradient to half the population at all steps



Pourchot, A. & Sigaud, O. (2018) CEM-RL: Combining evolutionary and gradient-based methods for policy search. *arXiv preprint arXiv:1810.01222* (ICLR 2019)

ERL follow-up: CERL



- ▶ CERL: ERL with a population of TD3 actors
- ▶ Similar to ERL, but:
 - ▶ Uses TD3 instead of DDPG
 - ▶ Uses a population of actors sharing the same critic
 - ▶ Does not evolve their hyper-parameters, as in PBT



Other follow-up

- ▶ FIDI-RL: In ERL, replaces the GA with Augmented Random Search
- ▶ ESAC: In ERL, replaces DDPG with SAC
- ▶ CEM-ACER: In CEMRL, replaces TD3 with ACER



Mania, H., Guy, A., and Recht, B. Simple random search of static linear policies is competitive for reinforcement learning. *Advances in Neural Information Processing Systems*, 31, 2018



Shi, L., Li, S., Cao, L., Yang, L., Zheng, G., and Pan, G. Fidi-RL: Incorporating deep reinforcement learning with finite-difference policy search for efficient learning of continuous control. *arXiv preprint arXiv:1907.00526*, 2019



Suri, K., Shi, X. Q., Plataniotis, K. N., and Lawryshyn, Y. A. Maximum mutation reinforcement learning for scalable control. *arXiv preprint arXiv:2007.13690*, 2020



Tang, Y. (2021) Guiding evolutionary strategies with off-policy actor-critic. In *Proceedings of the 20th International Conference on Autonomous Agents and MultiAgent Systems*, pages 1317–1325

ERL Limitations

- ▶ With direct encoding of NN parameters, the standard n -point crossover and mutations can be disruptive.
- ▶ PDERL replaces them with:
 - ▶ A combined policy distillation operator for crossover, inspired from Gangwani & Peng (2017)
 - ▶ The safe mutation operator of Lehman et al. (2018)



Bodnar, C., Day, B., and Lió, P. Proximal distilled evolutionary reinforcement learning. In *Proceedings of the AAAI Conference on Artificial Intelligence*, volume 34, pp. 3283–3290, 2020

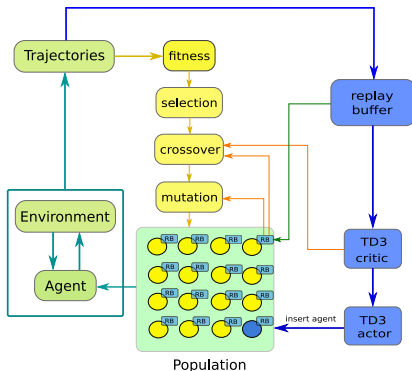


Gangwani, T. and Peng, J. Policy optimization by genetic distillation. *arXiv preprint arXiv:1711.01012*, 2017



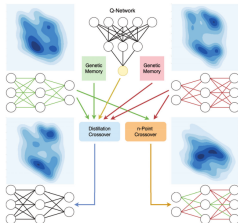
Lehman, J., Chen, J., Clune, J., and Stanley, K. O. Safe mutations for deep and recurrent neural networks through output gradients. In *Proceedings of the Genetic and Evolutionary Computation Conference*, pp. 117–124, 2018

PDERL Architecture



- ▶ Genetic memory: small local replay buffer
- ▶ Code available at <https://github.com/crisbodnar/pderl>.

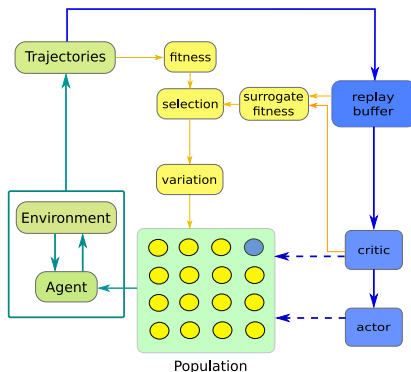
PDERL: New crossover: based on experience



- ▶ Each worker has its own replay buffer
- ▶ Crossover is between the replay buffers of parents
- ▶ The choice of parents is based on:
 - ▶ Greedy: the sum of their fitnesses
 - ▶ Diversity: the sum of their parameter distances

- ▶ Which choice is used is not specified nor studied!
- ▶ If policies are stochastic, one could use their KL divergence
- ▶ In an ERL-like approach, the most distant policy is often the TD3 agent
- ▶ The choice of samples is based on their Q -value, according to the central critic
- ▶ Offspring trained with behavioral cloning based on its synthetic replay buffer

SC-ERL (Surrogate-Assisted Controller)

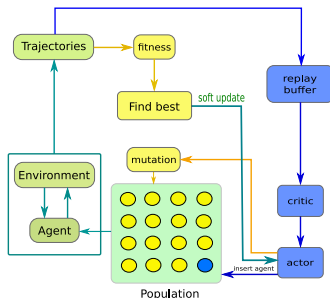


- ▶ The SC component is generic, it can be plugged into most Evo+RL algos
- ▶ The critic gives the surrogate fitness over a set of states taken from the replay buffer



Wang, Y., Zhang, T., Chang, Y., Wang, X., Liang, B., and Yuan, B. (2022) A surrogate-assisted controller for expensive evolutionary reinforcement learning. *Information Sciences*, 616:539–557

Supe-RL



- ▶ In ERL, CERL, CEMRL, the main loop is evolutionary, the RL loop generates faster improvement
- ▶ In SUPE-RL, the main loop is the RL loop, from time to time it performs an evolutionary step and improve the RL agent if a better offspring is found
- ▶ Performs a soft update of the RL agent towards the best offspring



Marchesini, E., Corsi, D., and Farinelli, A. Genetic soft updates for policy evolution in deep reinforcement learning. In *International Conference on Learning Representations*, 2021

Any question?



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Khadka, S., Majumdar, S., Miret, S., Tumer, E., Nassar, T., Dwiell, Z., Liu, Y., and Tumer, K. (2019).

Collaborative evolutionary reinforcement learning.

arXiv preprint arXiv:1905.00976.



Khadka, S. and Tumer, K. (2018).

Evolution-guided policy gradient in reinforcement learning.

In *Neural Information Processing Systems*.



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ACM Transactions in Evolutionary Learning and Optimization.



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